

Spectral Corrected Semivariogram Models¹

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Fitting semivariograms with analytical models can be tedious and restrictive. There are many smooth functions that could be used for the semivariogram; however, arbitrary interpolation of the semivariogram will almost certainly create an invalid function. A spectral correction, that is, taking the Fourier transform of the corresponding covariance values, resetting all negative terms to zero, standardizing the spectrum to sum to the sill, and inverse transforming is a valuable method for constructing valid discrete semivariogram models. This paper addresses some important implementation details and provides a methodology to working with spectrally corrected semivariograms.

KEY WORDS: nested structures, kriging, stochastic simulation, geostatistics, Fourier transform.

INTRODUCTION

The random function paradigm of semivariogram based geostatistics depends heavily on the calculation and fitting of a reasonable semivariogram model. The inference step is largely automatic once a decision of stationarity is taken and a semivariogram model is chosen. This paper is aimed at the determination of a valid semivariogram model. A *valid* semivariogram model is one that is conditionally non-negative definite and that does not lead to numerical artifacts due to instability. The conventional method of modeling semivariograms by nested structures is well established (Journel and Huijbregts, 1978). While this provides a workable mechanism for modeling most semivariograms, there are some cases that are not well fit with this framework. Figure 1 shows an example structure commonly observed in experimental semivariograms that is not easy to fit with the conventional structures. The largely unexplored suite of valid models, known as

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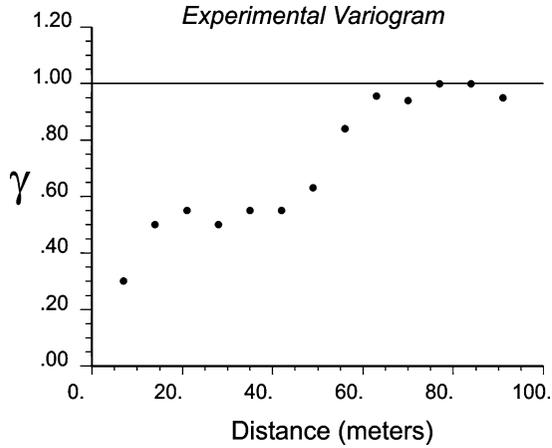


Figure 1. An example semivariogram that is not well fit by nested sets of traditional semivariogram models.

26 *geometric semivariograms*, is explored in a companion paper (Pyrcz and Deutsch,
 27 in press).

28 The covariance is related to the semivariogram under second order station-
 29 arity, $C(\mathbf{h}) = \sigma^2 - \gamma(\mathbf{h})$, and covariances will be referred to when it is standard
 30 practice to call on the covariance and not the semivariogram.

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32 Fitting an arbitrary function to experimental semivariogram points, $\gamma(\mathbf{h})$, does
 33 not guarantee a valid model for subsequent estimation and simulation. Spectral
 34 correction offers an efficient means to correct arbitrary fitted semivariogram to be
 35 conditional negative definite.

Bochner's theorem defines the general form of a conditional negative definite
 function $C(h)$, continuous in $h = 0$ (without nugget effect), as:

$$C(h) = \int_{-\infty}^{\infty} \cos(\omega h) dS(\omega) \tag{1}$$

36 under the constraints that $dS(\omega) > 0$ and $\int_{-\infty}^{\infty} dS(\omega) = C(0) < \infty$. $S(\omega)$ is the
 37 spectral cumulative distribution function.

38 The link between the spectrum and covariance models is an efficient method to
 39 check for conditional negative definiteness and to correct for conditional negative
 40 definiteness in semivariogram models. A check of the spectrum representation

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amounts to checking if all real components are greater than 0.0 and that they sum to the variance ($C(0)$).

In practice, this is accomplished with a discrete fast Fourier transform (FFT), resulting in a discrete solution. A discrete covariance model, or covariance table, is corrected by enforcing these constraints by setting all negative real components to 0.0 and then standardizing all spectrum to sum to the variance.

PROPOSED FLEXIBLE SEMIVARIOGRAM MODELING PROCEDURE

A new methodology for flexible semivariogram modeling is proposed. This methodology requires the following steps: (1) freely model the semivariogram in a suite of representative directions, (2) construct a consistent covariance table from the directional semivariograms and (3) correct the covariance tables for conditional negative definiteness. The corrected covariance tables may be loaded directly into kriging or simulation programs. Each of these steps are discussed in greater detail below.

These directional models may be regression fits of the experimental semivariogram points, or even hand drawn. The added flexibility allows for the integration of calculated experimental statistics and geologic information.

A covariance table will be inferred from the directional semivariograms. The covariance table must have the same dimensionality and scale as the random function model to which it will be applied. The table is set large enough that the semivariogram fully characterizes spatial continuity (i.e. extends to the range in each direction). Also, the size of the table is set to a power of 2.

$$ncells_{x,y,z} = 2^{i_{x,y,z}} \tag{2}$$

where $i_{x,y,z}$ is an integer. This is required by the Numerical Recipes multidimensional discrete FFT subroutine (fourn.for) (Press, Flannery, and Teukolsky, 1992, p. 499).

The traditional linear model of regionalization requires that the semivariogram is inferred for directions other than the principals by applying geometric anisotropy [Eq. (2)] (Isaaks and Srivastava, 1989, p. 377). This method requires the directional semivariograms to be constructed from a common set of nested structures. Each nested structure must be effective over all directions. Because we have not applied a common set of nested structures, we require a new method to infer the semivariogram in the non-principal directions.

The method proposed here is based on variable geometric anisotropy. This method is limited by two assumptions: (1) the semivariogram is provided in the principal directions and (2) the semivariogram models are monotonically increasing (no cyclicity or hole effect).

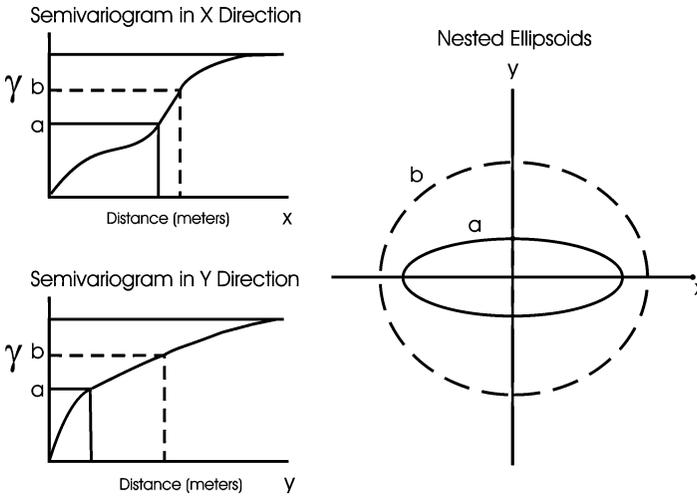


Figure 2. Variable geometric anisotropy: the anisotropy ratios are allowed to vary with respect to semivariogram contribution. This results in the ability to consistently infer the semivariogram model in off-diagonal directions when the principal directions are not modeled by nested structures that exist in all directions. In this example the semivariogram is strongly anisotropic for the short range and then becomes more isotropic over the long range.

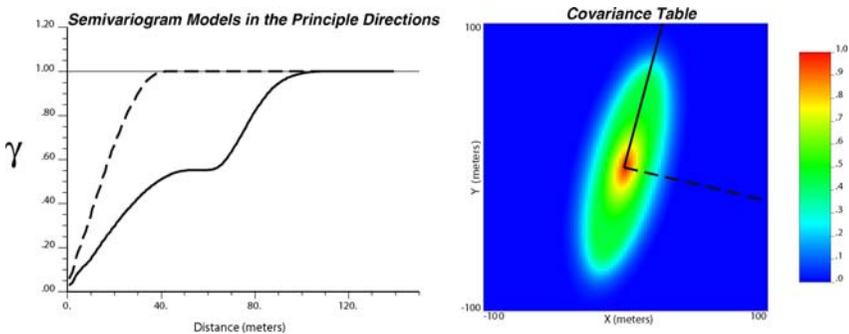


Figure 3. The semivariogram models for the principal directions and the resulting covariance table. The covariance table is inferred with variable anisotropy.

72 Variable geometric anisotropy is applied as follows: (1) the semivariogram
 73 model is binned by equal variance contributions, (2) the ranges in the principal
 74 directions are tabulated for each bin. These ranges parameterize nested ellipsoids
 75 that define the semivariogram in all directions with variable geometric anisotropy.
 76 These ellipsoids are demonstrated in Figure 2 and are represented by well known
 77 equation for an ellipsoid.

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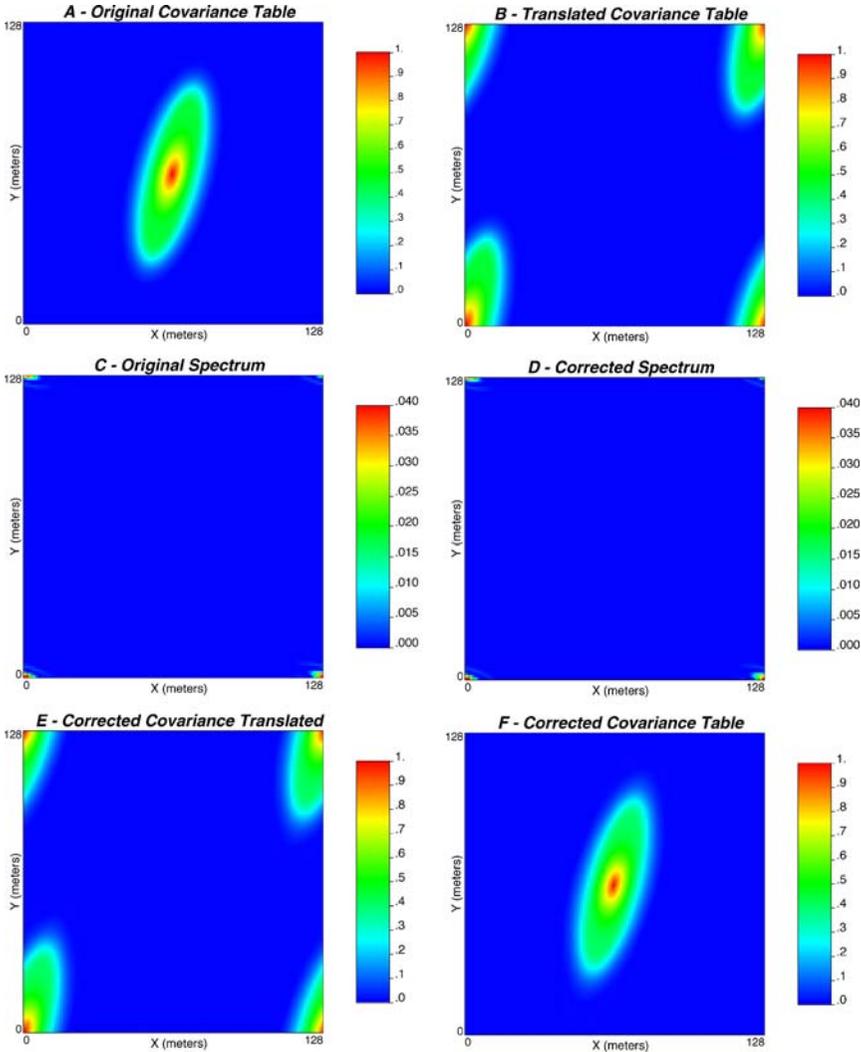


Figure 4. The steps to correct the A, covariance table. (1) translate the covariance table so that the origin is located at the table corners, B, (2) apply the discrete FFT to the table, C, (3) correct the spectrum, D, and then (4) perform the inverse FFT, E, and (5) translate the corrected covariance table origin back to the center of the table, F.

For all locations within the covariance table, the covariance value associated with the closest ellipsoid to the location is assigned. This is calculated quickly by solving the equation for each ellipsoid proceeding from the smallest to the largest. The application of many bins results in a smooth interpolation of the off-diagonal semivariograms.

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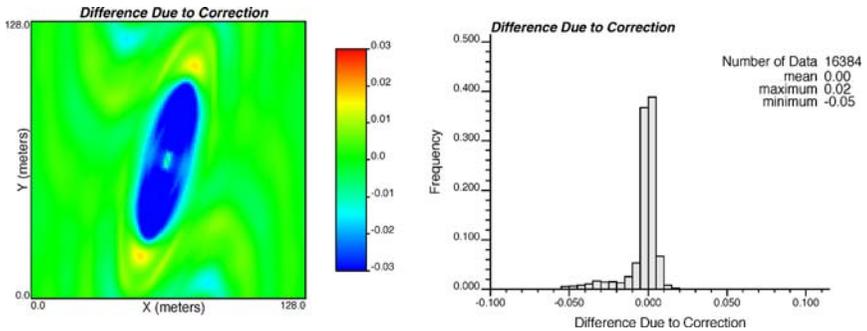


Figure 5. The difference in the covariance table due to correction (corrected–original).

83 The application of nested ellipsoids for inferring the off-diagonal semivari-
 84 ogram is demonstrated for a 2-D example in Figure 3. The example 2-D covariance
 85 table was calculated from semivariogram models in the principal directions defined
 86 by flexible fit models. The semivariogram model in Figure 3 would not
 87 be possible with conventional semivariogram modeling techniques. Of course,
 88 there is no guarantee that the resulting covariance table in Figure 3 is conditional
 89 negative definite. This will be dealt with in the next section.

90

Correct the Covariance Table

91 The previously outlined method of applying constraints in the spectrum
 92 representation is applied to correct for conditional negative definiteness. The
 93 practical steps include (1) translate the covariance table so that the origin is
 94 located at the table corners, (2) apply the discrete FFT to the table, (3) correct
 95 the spectrum by to be positive definite and then (4) perform the inverse FFT
 96 and (5) translate the corrected covariance table origin back to the center of the
 97 table. These steps are demonstrated for the example covariance table (Fig. 3) in
 98 Figure 4.

99 For the example covariance table the magnitude of correction is characterized
 100 by a plot of the difference between the original and the corrected covariance table
 101 and the histogram of the difference (Fig. 5). Maximum change in this case is about
 102 5% of the sill. The original and corrected semivariogram models are shown for
 103 the principal and two off-diagonal directions along with the corrected covariance
 104 table (Fig. 6).

105 This method has some similarities to the methodology proposed by Yao and
 106 Journel (1998). The key difference is in the construction of the covariance tables.
 107 Our method focuses on the integration of geologic information through the flexible
 108 design of semivariogram models in the principal directions and the construction

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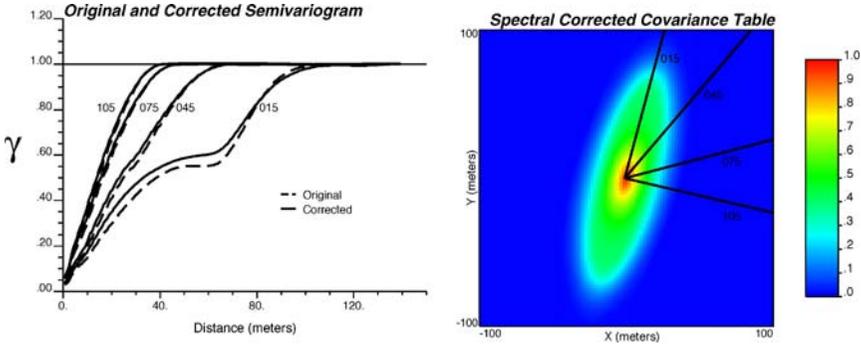


Figure 6. A comparison of directional semivariograms from the original and corrected covariance tables.

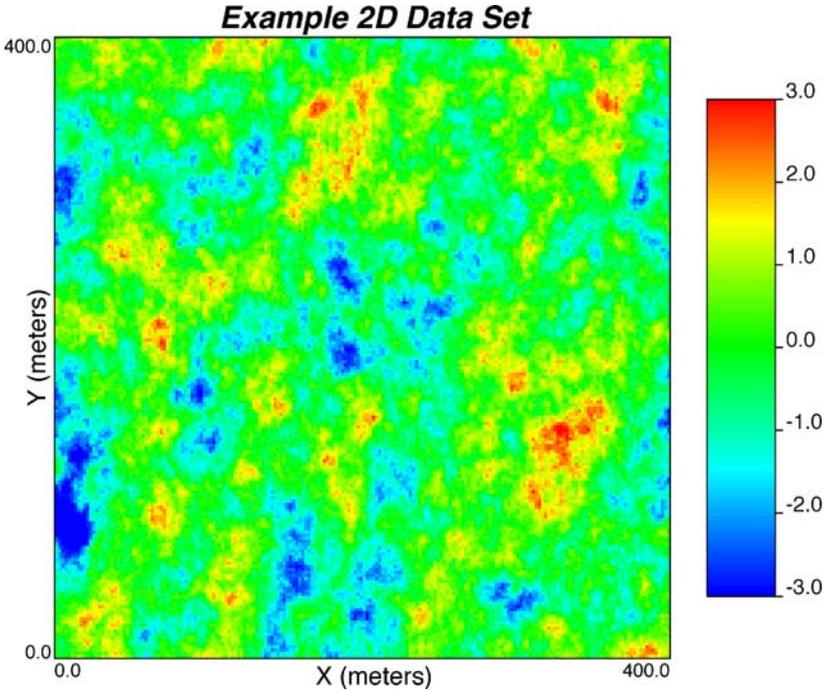


Figure 7. An example 2D exhaustive data set.

of a consistent covariance table. The Yao and Journel (1998) method automatically constructs the covariance table directly from the available sample data and then applies a preliminary smoothing to remove noise due to sparse data. The resulting smoothed covariance map is then corrected in spectrum for conditional

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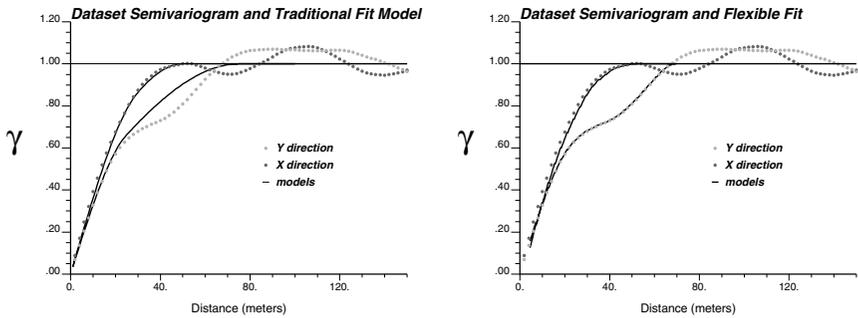


Figure 8. The experimental semivariograms and the fit models based on the (1) traditional method of nested conditional negative definite models and (2) flexible semivariogram modeling method. The semivariogram is modeled to the sill since the model will be applied in sequential Gaussian simulation.

113 negative definite ness as outlined previously. While this method streamlines the
 114 semivariogram modeling process, it may remove the opportunity to inject geo-
 115 logic information with respect to the heterogeneity and anisotropy and risks the
 116 possibility of over fitting noisy experimental data.

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DEMONSTRATION

118 The application of spectral corrected semivariogram models is demonstrated.
 119 An example 2-D data set is shown in Figure 7. An exhaustive data set was applied
 120 to remove issues related to model inference and to focus on flexible semivariogram
 121 model construction. This data set is an unconditional sequential Gaussian simu-
 122 lation realization with spatial structures not well modeled with nested structures.
 123 The semivariograms were modeled in the principal directions (aligned with the X
 124 and Y coordinates). The resulting semivariograms fitted by (1) traditional method
 125 of nested structures and (2) flexible semivariogram modeling method as shown in
 126 Figure 8. The flexible semivariogram modeling method resulted in a conditional
 127 negative definite semivariogram model that closely characterizes the directional
 128 experimental semivariograms.

129

CONCLUSION

130 The choice of semivariogram model has a major affect on kriging and kriging-
 131 based simulation models. Spectral corrected models offer an efficient methodology
 132 for improving semivariogram modeling. This technique allows semivariograms to
 133 be modeled with greater emphasis on geologic continuity information as opposed

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to limits imposed by the traditional method of nested structures. In practice the 134
corrected semivariogram models are not so different from the uncorrected shapes. 135
Many practitioners would like to fit directional semivariograms independently and 136
then reconcile them in software. This provides a practical solution. 137

The required computer code is straightforward and mostly available in the 138
public domain. All semivariogram models proposed here are guaranteed to be 139
valid; therefore, there are no issues with implementation. 140

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